

# Introduction:

Orthopedic implant failure stems more from uncontrolled implantation energy and poor load transfer than alignment error. We present a physics-based, AI-enabled framework that treats implantation as a closed-loop energetic process and integrates load-path implant architecture to achieve deterministic fixation and preserve bone mechanics.

Provisional Applications

**63/756,278 (internal 7138)**

**63/765,699 (internal 7139)**

US Utility Application

**19/533,256 (internal 7145)**

PCT application

**PCT/US26/14517 (Internal 7146)**

# PERSPECTIVE

## THE MECHANICS FRONTIER IN ORTHOPEDICS

From Geometry to Mechanics: Closed-Loop Implantation and Load-Path Design

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### **Introduction: A Coupled Mechanical Failure in Modern Orthopedics**

Despite remarkable advances in implant materials, manufacturing, and surgical navigation, orthopedic implant longevity remains constrained by two fundamental mechanical failures that arise at distinct but tightly coupled stages of treatment. The first occurs during implantation, where contemporary surgical practice — including robotic assistance — remains overwhelmingly focused on kinematics rather than kinetics. The second emerges during service life, where the structural architecture of implants governs long-term load transfer and fatigue durability. Together, these failures form a closed mechanical loop in which early damage initiated by uncontrolled force application is compounded by structurally inappropriate load-bearing strategies.

This perspective argues that the prevailing emphasis on geometric precision and porous architectural optimization has obscured deeper first-principles mechanical violations. Specifically, high-energy implantation processes remain uncontrolled, and fatigue-critical loads are routinely entrusted to cellular architectures inherently prone to stress concentration and crack initiation. Resolving these coupled failures requires reframing both implantation as an energetic control problem and implant design as a load-path engineering challenge.

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### **Kinematics Without Kinetics: The Hidden Damage of Implantation**

Modern orthopedic surgery increasingly prioritizes alignment accuracy, positional repeatability, and geometric optimization. Navigation systems and surgical robotics have achieved impressive gains in spatial precision, yet implantation itself remains a fundamentally energetic process executed with minimal mechanical feedback or control. Hammering, high-energy press-fit impacts, vibratory insertion techniques, reaming, and broaching are routinely employed to prepare and seat implants within bone. These procedures impose substantial transient forces and energy flux at the bone–implant interface, yet occur without real-time measurement or regulation of applied force, energy transfer, or interface impedance.

The mechanical consequences are well known yet rarely quantified intraoperatively. Microfracture of trabecular bone, cancellous crushing, cortical microdamage, and disruption of

early interface stability are frequently induced during implantation. Because such damage is often subclinical and undetectable by conventional imaging, it is routinely accepted as an unavoidable aspect of surgery. However, these mechanically driven injuries degrade primary fixation, alter local mechanobiological signaling, and accelerate loosening and fatigue processes long before macroscopic failure becomes apparent.

The prevailing paradigm thus treats implantation as a geometric problem rather than a controlled mechanical interaction. By ignoring kinetics and energy management, orthopedics tolerates early damage that fundamentally compromises long-term implant performance.

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## **Structurally Inappropriate Implants: The Failure of Both Bulk and Porous Extremes**

Following implantation, the mechanical fate of the construct is governed by the architecture of the implant itself. Contemporary designs largely occupy two opposing but equally flawed extremes.

Bulk solid metal implants offer excellent strength and fatigue resistance but are excessively stiff relative to surrounding bone. This stiffness mismatch redistributes physiological loads away from bone and into the implant, producing stress shielding, progressive bone resorption, and long-term deterioration of fixation. While mechanically durable, these devices undermine the biological environment required for sustained osseointegration and healthy remodeling.

Porous and lattice implants were introduced to address this limitation by providing compliance, enhanced surface area, and improved biological integration. While conceptually appealing, such architectures have consistently demonstrated poor fatigue performance in load-bearing orthopedic applications. Stress concentrations at strut junctions, node-driven crack initiation, surface roughness, internal defects from additive manufacturing, and geometric sensitivity to minor imperfections collectively lead to premature failure under cyclic loading. Despite decades of optimization, the biological promise of porosity has not structurally materialized for fatigue-critical implants.

Thus, orthopedics oscillates between mechanically durable but biologically hostile bulk structures and biologically promising but mechanically fragile cellular networks — without resolving the underlying mechanical conflict.

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## **A Universal Engineering Principle Violated**

At its core, this conflict reflects a violation of a universal engineering principle: fatigue-critical load paths should never be carried by cellular architectures, and high-energy mechanical processes should never be left uncontrolled. In mature engineering disciplines — including bridge design, aerospace structures, reinforced concrete systems, and architectural frameworks

— primary stresses are deliberately carried by continuous bulk elements specifically engineered for fatigue durability. Distributed materials are then employed to tune compliance, interaction, and functional response without compromising structural integrity. Equally important, energy input during assembly and operation is actively managed to prevent damage accumulation.

Orthopedic implant design has inverted both principles. Cellular architectures are routinely entrusted with primary structural loads, while energetic implantation processes are performed with minimal feedback or regulation. The result is a mechanically fragile system prone to early damage and long-term failure.

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## **Load-Path Reinforced Cellular Metal Architecture**

To address these foundational issues, a composite implant architecture is proposed that explicitly separates fatigue-critical load bearing from biological and mechanical compliance. Primary structural loads are carried by bulk-material framework elements — including longitudinal ribs, circumferential planks, and tubular spines — which provide the crack resistance, continuity, and fatigue strength characteristic of solid metals. These elements define engineered load paths through the implant, ensuring that cyclic stresses bypass fragile cellular junctions.

Surrounding and embedding this framework is a cellular metal matrix whose role is not structural load bearing but mechanical tuning and biological integration. The matrix modulates effective stiffness to mitigate stress shielding, distributes loads gradually into surrounding bone, and provides extensive surface area for osseointegration. By relegating the cellular architecture to compliance and biological function while reserving load bearing for fatigue-durable frameworks, this approach reconciles long-standing tradeoffs between mechanical longevity and physiological performance.

The resulting system achieves high fatigue durability, controlled compliance, elimination of node-driven failure mechanisms, and preservation of physiological load transfer — capabilities unattainable by either bulk or porous architectures alone.

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## **Force-Aware Implantation: Reintroducing Kinetics Into Surgical Practice**

Architectural redesign alone is insufficient if early mechanical damage continues to be induced during implantation. Accordingly, implantation is reframed as a closed-loop energetic control process rather than a geometric task. Real-time estimation of applied force, interface impedance, and energy transfer enables detection of bone elastic limits during preparation and seating. Physics-informed control algorithms regulate energy input to achieve secure fixation while preventing microdamage, cancellous crushing, and cortical fracture.

By actively managing the mechanical environment of implantation, early sources of instability and fatigue initiation are eliminated at their origin. The implant–bone interface is preserved as a mechanically healthy system rather than a damaged compromise.

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## **Escaping the Porous Optimization Loop**

Rather than endlessly refining lattice geometries in pursuit of marginal fatigue improvements, this framework fundamentally redefines the mechanical problem. Structural load bearing is deliberately separated from biological compliance, and energetic insertion processes are actively controlled rather than tolerated. Together, these principles resolve both the early damage produced by uncontrolled force application and the long-term failure driven by structurally inappropriate implant architectures.

This integrated mechanical ecosystem unites fatigue mechanics, architected materials, bone biomechanics, and force-controlled robotics into a deterministic system extending from implantation through service life. It represents a shift from geometry-centric optimization toward first-principles mechanical design.

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## **Concluding Perspective**

Orthopedic implant failure is not primarily a materials problem, a geometric problem, or a manufacturing problem. It is a mechanics problem rooted in uncontrolled energy application and misallocated structural responsibility. By reintroducing kinetics into surgical control and reengineering implants around explicit load paths supported by fatigue-durable frameworks, it becomes possible to simultaneously preserve biological performance and achieve long-term mechanical durability.

This perspective suggests that the future of orthopedics lies not in ever-finer lattice optimization but in mechanically honest systems that respect universal structural principles — systems in which force is actively managed and architecture is purposefully engineered to carry it.